Q1. On the Barbara image, you have to simulate slat and pepper noise. Then you have to implement the median filter to denoise it. Then you need to compute the Peak Signal to Noise Ratio (PSNR) between the clean image and denoised image.

Images need to be embedded in the following table. You will need to specify the best window size for each level of noise.

| Noisy Image | Noisy Image [embed] | Best Denoised Image [embed] | PSNR | Parameter(s) of median filter for best denoising |
| --- | --- | --- | --- | --- |
| 5% corrupted pixels |  |  | 14.06388 | 5\*5 kernel |
| 15% corrupted pixels |  |  | 9.9594622 | 5\*5 kernel |
| 20% corrupted pixels |  |  | 8.84052296 | 7\*7 kernel |
| 25% corrupted pixels |  |  | 7.921379 | 7\*7 kernel |

5 marks

Q2. Take the cameraman image. Now reduce its size by 16 times, i.e. if the original image is 256x256, your reduced image should be 64x64. Your task is to super-resolve the 64x64 image by 16 times.

This question is kept intentionally open ended. Try out 5 interpolation kernels (e.g. nearest neighbour, linear, splines etc.) from the class notes to get the best results. You can compare the results based on PSNR between the original 256x256 image and the super-resolved image.

| Interpolation Kernel | PSNR | Embed super-resolved Image |
| --- | --- | --- |
| NN | 24.01093 |  |
| Bi\_Linear | 21.71993 |  |
| cubic\_interpolation | 33.160042 |  |
| linear | 32.984441 |  |
| spline | 33.156334 |  |

5 marks